On Non-invariant Hypersurfaces of a Nearly Kenmotsu Manifold

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Abstract: The object of this paper is to study non-invariant hypersurfaces of a nearly Kenmotsu manifold equipped with (f, g, u, v, λ) - structure. Some properties obeyed by this structure are obtained. The necessary and sufficient conditions also have been obtained for totally umbilical non-invariant hypersurfaces with (f, g, u, v, λ) - structure of nearly Kenmotsu manifold to be totally geodesic. The second fundamental form of a non-invariant hypersurfaces of a nearly Kenmotsu manifold with (f, g, u, v, λ) - structure has been traced under the condition when f is parallel.

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I. Introduction

In 1970, *S.I.Goldberg et. al*¹ introduced the notion of a non-invariant hypersurfaces of an almost contact manifold in which the transform of a tangent vector of the hypersurface by the (1,1) structure tensor field f defining the almost contact structure is never tangent to the hypersurface. The notion of (f, g, u, v, λ) - structure was given by $K.Yano^2$. It is well $known^{3.4}$ that hypersurfaces of an almost contact metric manifold always admits a (f, g, u, v, λ) - structure. Authors¹ proved that there always exists a (f, g, u, v, λ) - structure on a non-invariant hypersurface of an almost contact metric manifold. They also proved that there does not exist invariant hypersurface of a contact manifold. *R. Prasad*^{5.7} studied the non-invariant hypersurfaces of trans-Sasakian manifolds and nearly Sasakian manifolds. In the present paper, we study the non-invariant hypersurfaces of nearly Kenmotsu manifolds.

The paper is organized as follows. In section 2, we give a brief description of nearly Kenmotsu manifold. In section 3, introduce the non-invariant hypersurfaces and induced (f, g, u, v, λ) - structure on non-invariant hypersurface M getting some equation. Some results of non-invariant hypersurfaces with (f,g,u,v,λ) - structure of nearly Kenmotsu manifold. The necessary and sufficient conditions also have been obtained for totally umbilical non-invariant hypersurfaces with (f,g,u,v,λ) - structure of nearly Kenmotsu manifold to be totally geodesic. The second fundamental form of a non-invariant hypersurfaces of a nearly Kenmotsu manifold with (f, g, u, v, λ) -structure has been traced under the condition when f is parallel.

II. Preliminaries

Let \overline{M} be an (2n + 1)-dimensional almost contact metric manifold with a metric g, tensor field \emptyset of type(1,1), a vector field ξ , a dual 1-form η which are satisfying the following $\phi^2 X = -X + \eta(X)\xi, \ \eta(\xi) = 1, \ \phi(\xi) = 0, \ \eta o \phi = 0$ (2.1) $g(\emptyset X, \emptyset Y) = g(X, Y) - \eta(X)\eta(Y)$ (2.2)for any X, Y tangent to \overline{M} . If addition to the above condition we have $g(\emptyset X, Y) = -g(\emptyset Y, X), \quad g(X, \xi) = \eta(X)$ (2.3)The structure is said to be contact metric structure. An almost contact metric Manifold \overline{M} is called nearly Kenmotsu manifold if it satisfy the condition [6] $(\overline{\nabla}_X \phi)Y + (\overline{\nabla}_Y \phi)X = -\eta(Y)\phi X - \eta(X)\phi Y$ (2.4)Where $\overline{\nabla}$ denote the Riemannian connection with respect to g, if moreover M sathisfies $(\overline{\nabla}_X \emptyset) Y = g(\emptyset X, Y) \xi - \eta(Y) \emptyset X$ Then it is called Kenmotsu manifold [6]. Obliviously, a Kenmotsu manifold is also a nearly Kenmotsu manifold. From (2.4), we have $\overline{\nabla}_X \xi = X - \eta(X)\xi - \emptyset((\overline{\nabla}_\xi \phi)X).$ (2.5)

A hypersurface of an almost contact metric manifold \overline{M} on $(\emptyset, \xi, \eta, g)$ is called a non-invariant hypersurfaces, if the transform of a tangent vector of the hypersurface under the action of (1,1) tensor field \emptyset defining the contact structure is never tangent to the hypersurface.

Let X be a tangent vector on a non-invariant hypersurfaces of an almost contact metric manifold \overline{M} , then $\emptyset X$ is never tangent to the hypersurface.

Let M be a non-invariant hypersurfaces of an almost contact metric manifold. Now, if we define the following, $\emptyset X = f X + u(X)\overline{N}$ (2.6)

$\phi \overline{N} = -U$	(2.7)
$\xi = V + \lambda \overline{N} , \lambda = \eta(\overline{N})$	(2.8)
$\eta(X) = \nu(X)$	(2.9)

where f is (1,1) tensor field, u & v are 1-form, \overline{N} is a unit normal to the hypersurfaces, $X \in TM \& u(X) \neq 0$, then we get an induced (f, g, u, v, λ) - structure on M satisfying the condition.^{2,3}

Making use of (2.6)	, (2.7), (2.8) & (2.	9) through equations	(2.1) to (2.4), we have
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$f^2 = -I + u \otimes U - v \otimes V$	(2.10)
$uof = \lambda v, vof = -\lambda u$	(2.11)
$v(V) = 1 - \lambda^2$, $u(V) = v(U) = 0$, $u(U) = 1 - \lambda^2$	(2.12)
$fV = \lambda U, fU = -\lambda V$	(2.13)
$g(X, U) = u(X), \ g(X, V) = v(X)$	(2.14)
g(fX, fY) = g(X, Y) - u(X)u(Y) - v(X)v(Y)	(2.15)
g(fX,Y) = -g(fY,X)	(2.16)
for all $X, Y \in TM \& \lambda = \eta(\overline{N})$.	
The Gauss & Weingarten formula are given by	
$\overline{\nabla}_X Y = \nabla_X Y + h(X, Y)\overline{N}$	(2.17)
$\overline{\nabla}_X \overline{N} = -A_{\overline{N}} X(2.18)$	(2.18)
for all $X, Y \in TM$, where $\nabla \& \overline{\nabla}$ are the Riemannian & induced connection on $\overline{M} \& M$ respectively a	$\sqrt[6]{N}$ is the unit
normal vector in the normal bundle $T^{\perp}M$.	
In this formula h is the second fundamental form on M related to A_N by	
$h(X,Y) = g(A_{\bar{N}}X,Y)$	(2.19)

for all $X, Y \in T$

III. Non-invariant Hypersurfaces

Lemma 3.1. If *M* be a non-invariant hypersurfaces with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , then $(\overline{M}, r)K + (\overline{M}, r)K = (\overline{M}, r)K + ($

$$(\nabla_X \eta)Y + (\nabla_Y \eta)X = (\nabla_X v)Y + (\nabla_Y v)X - 2\lambda h(X, Y)$$

$$(3.1)$$

$$(3.2)$$
for all $X, Y \in TM.$

Proof. After computations similar to lemma 3.1 in [7], lemma follows.

Theorem 3.2. If M be a non-invariant hypersurface with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , then

$$(\nabla_X f)Y + (\nabla_Y f)X = u(X)A_{\overline{N}}Y + u(Y)A_{\overline{N}}X - 2h(X,Y)U - v(X)fY - v(Y)fX$$

$$(\nabla_X u)Y + (\nabla_Y u)X = -u(X)v(Y) - u(Y)v(X) - h(X,fY) - h(Y,fX)$$

$$(3.4)$$
for all $X, Y \in TM.$

Proof.By covariant differentiation, we know that

 $\begin{aligned} (\overline{\nabla}_X \phi) Y &= \overline{\nabla}_X \phi Y - \phi(\overline{\nabla}_X Y) \\ \text{Using equation (2.6), (2.7) and (2.17) in above equation, we have} \\ (\overline{\nabla}_X \phi) Y &= \overline{\nabla}_X (fY + u(Y)\overline{N}) - \phi(\nabla_X Y + h(X,Y)\overline{N}) \\ (\overline{\nabla}_X \phi) Y &= (\nabla_X f) Y - u(Y) A_{\overline{N}} X + h(X,Y) U + ((\nabla_X u) Y) \overline{N} + h(X, fY) \overline{N} \end{aligned} (3.5) \\ \text{Similarly, we have} \\ (\overline{\nabla}_Y \phi) X &= (\nabla_Y f) X - u(X) A_{\overline{N}} Y + h(X,Y) U + ((\nabla_Y u) X) \overline{N} + h(Y,fX) \overline{N} \\ \text{Adding equation (3.5) & (3.6), we have} \\ (\overline{\nabla}_X \phi) Y + (\overline{\nabla}_Y \phi) X &= (\nabla_X f) Y + (\nabla_Y f) X + 2h(X,Y) U - u(Y) A_{\overline{N}} X - u(X) A_{\overline{N}} Y \\ &+ ((\nabla_X u) Y) + ((\nabla_Y u) X) + h(X, fY) + h(Y, fX)) \overline{N} \end{aligned} (3.7) \\ \text{Now using equation (2.6) and (2.9) in (2.4), we have} \\ (\overline{\nabla}_X \phi) Y + (\overline{\nabla}_Y \phi) X &= -v(X) (fY) - v(X) u(Y) \overline{N} - v(Y) (fX) - v(Y) u(X) \overline{N} \end{aligned} (3.8)$

From equation (3.7) and (3.8), comparing tangential and normal part, we have the desired results.

Theorem 3.3. If *M* be a non-invariant hypersurfaces with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , then

$$h(X,\xi)U = f(\nabla_X\xi) - fX + f^2((\overline{\nabla}_{\xi}\phi)X) - u((\overline{\nabla}_{\xi}\phi)X)U$$

$$u(\nabla_X\xi) = u(X) - u(f((\overline{\nabla}_{\xi}\phi)X))$$
(3.9)
(3.10)
for all $X, Y \in TM$.

Proof. Let us consider $(\overline{\nabla}_{X}\phi)\xi = \overline{\nabla}_{X}\phi\xi - \phi(\overline{\nabla}_{X}\xi)$ (3.11) Using equation (2.1), (2.5) & (2.6), we have $(\overline{\nabla}_{X}\phi)\xi = -\phi(X - \eta(X)\xi - \phi((\overline{\nabla}_{\xi}\phi)X))$ ($\overline{\nabla}_{X}\phi)\xi = -fX + f^{2}((\overline{\nabla}_{\xi}\phi)X) - u((\overline{\nabla}_{\xi}\phi)X)U - u(X)\overline{N} + u(f((\overline{\nabla}_{\xi}\phi)X))\overline{N}$ (3.12) Since we know that $(\overline{\nabla}_{X}\phi)\xi = \overline{\nabla}_{X}\phi\xi - \phi(\overline{\nabla}_{X}\xi)$ Using (2.1), (2.6) & (2.17), we have $(\overline{\nabla}_{X}\phi)\xi = -f(\nabla_{X}\xi) - u(\nabla_{X}\xi)\overline{N} + h(X,\xi)U$ (3.13) Using (3.12), (3.13) and comparing tangential & normal part, we get the desired results.

Theorem 3.4.If *M* be a non-invariant hypersurfaces with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , then $(\overline{\nabla}_X \phi)Y + (\overline{\nabla}_Y \phi)X = -v(X)fY - v(Y)fX - (u(X)v(Y) + u(Y)v(X))\overline{N}$ (3.14) for all $X, Y \in TM$.

Proof. Using (3.3), (3.4) & (3.7), we have $(\overline{\nabla}_X \emptyset)Y + (\overline{\nabla}_Y \emptyset)X = u(X)A_{\overline{N}}Y + u(Y)A_{\overline{N}}X - u(X)A_{\overline{N}}Y + 2h(X,Y)U - 2h(X,Y)U - u(Y)A_{\overline{N}}X - u(X)A_{\overline{N}}Y + 2h(X,Y)U + (-u(X)v(Y) - u(Y)v(X) - h(X,fY) - h(Y,fX) + h(X,fY) + h(Y,fX))\overline{N}$ $(\overline{\nabla}_X \emptyset)Y + (\overline{\nabla}_Y \emptyset)X = -v(X)fY - v(Y)fX - (u(X)v(Y) + u(Y)v(X))\overline{N}.$ for all *X*, *Y* ∈ *TM*.

Theorem 3.5. If *M* be a totally umbilical non-invariant hypersurfaces with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , then it is totally geodesic if and only if $\lambda v(X) + u((\overline{\nabla}_{\xi} \emptyset)X) + X\lambda = 0$ (3.15) and in particular, if nearly Kenmotsu manifold admits a contact structure then (3.15) can be expressed as $v + d(\log \lambda) = 0$ (3.16) for all $X, Y \in TM$.

Proof. By Gauss formula, we have $\overline{\nabla}_X \xi = \nabla_X \xi + h(X,\xi)\overline{N}$ Using equation (2.8), we have $\overline{\nabla}_{X}\xi = \nabla_{X}V - \lambda A_{\overline{N}}X + (h(X,V) + X\lambda)\overline{N}$ (3.17)Using (2.6), (2.8) & (2.9) in (2.5), we have $\overline{\nabla}_X \xi = X - v(X)V - \lambda v(X)\overline{N} - f((\overline{\nabla}_\xi \phi)X) - u((\overline{\nabla}_\xi \phi)X)\overline{N}$ (3.18)From (3.17) & (3.18), we have $\nabla_{X}V - \lambda A_{\overline{N}}X + (h(X,V) + X\lambda)\overline{N} = X - v(X)V - \lambda v(X)\overline{N} - f((\overline{\nabla}_{\varepsilon}\phi)X) - u((\overline{\nabla}_{\varepsilon}\phi)X)\overline{N}$ Equating normal part, we have $h(X,V) = -\lambda v(X) - u((\overline{\nabla}_{\xi} \emptyset)X) - X\lambda$ (3.19)Now if *M* is totally umbilical then $A_{\overline{N}} = \zeta I$, where ζ is Kahlerian metric and (2.19) reduce into $h(X,Y) = g(A_{\overline{N}}X,Y) = g(\zeta X,Y) = \zeta g(X,Y)$ therefore, $h(X,Y) = \zeta g(X,Y) = \zeta g(X,\xi) = \zeta \eta(X)$ $\Rightarrow h(X,\xi) = \zeta v(X)$ So (3.19) reduce as $\lambda v(X) + u((\overline{\nabla}_{\xi} \emptyset)X) + X\lambda + \zeta v(X) = 0$ if *M* is totally umbilical i.e. $\zeta = 0$, then above becomes $\lambda v(X) + u((\overline{\nabla}_{\xi} \emptyset)X) + X\lambda = 0$ Now if nearly Kenmotsu manifold is equipped with contact structure, then above can be written as $\lambda v(X) + X\lambda = 0$ $\Rightarrow v + d(\log \lambda) = 0.$ for all $X, Y \in TM$.

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Theorem 3.6. If *M* be a non-invariant hypersurfaces with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , if U is parallel then we have $\lambda fX + f(A_{\overline{N}}X) + (\nabla_{\overline{N}}f)X - v(X)U = 0$ (3.20) for all $X, Y \in TM$.

Proof. Consider

 $(\overline{\nabla}_X \phi) \overline{N} = \overline{\nabla}_X \phi \overline{N} - \phi(\overline{\nabla}_X \overline{N})$ $(\overline{\nabla}_X \phi)\overline{N} = -\nabla_X U + f(A_{\overline{N}}X)$ (3.21)Now replacing Y by \overline{N} in (2.4), we have $(\overline{\nabla}_X \phi)\overline{N} + (\overline{\nabla}_{\overline{N}} \phi)X = -\eta(X)\phi\overline{N} - \eta(\overline{N})\phi X$ Using equation (2.6), (2.7), (2.8) & (2.9) in above, we have $(\overline{\nabla}_X \phi)\overline{N} + (\overline{\nabla}_{\overline{N}} \phi)X = v(X)U - \lambda fX - \lambda u(X)\overline{N})$ (3.22)Also we have $(\overline{\nabla}_{\overline{N}}\phi)X = (\nabla_{\overline{N}}f)X - u(X)A_{\overline{N}}\overline{N} + \{(\nabla_{\overline{N}}u)X + h(\overline{N}, fX)\}\overline{N}$ (3.23)Using equation (3.21) & (3.23) in (3.22), we have $-\nabla_{X}U + f(A_{\overline{N}}X) + (\nabla_{\overline{N}}f)X - u(X)A_{\overline{N}}\overline{N} + \{(\nabla_{\overline{N}}u)X + h(\overline{N}, fX)\}\overline{N} = v(X)U - \lambda fX - \lambda u(X)\overline{N}\}$ Equating tangential part, we have $\nabla_X U = \lambda f X + f(A_{\overline{N}}X) + (\nabla_{\overline{N}}f)X - v(X)U$ If *U* is parallel then we have $\lambda f X + f(A_{\overline{N}}X) + (\nabla_{\overline{N}}f)X - v(X)U = 0.$ for all $X, Y \in TM$.

Theorem 3.7. If *M* be a non-invariant hypersurfaces with (f, g, u, v, λ) – structure of a nearly Kenmotsu manifold \overline{M} , if *f* is parallel then we have

$$h(X,Y) = \frac{\mu}{1-\lambda^2} u(X)u(Y) - \frac{1}{2(1+\lambda^2)} (v(X)u(fY) + v(Y)u(fX))$$
(3.24)
Where $\mu = h(U,U) = g(A_{\overline{N}}U,U)$, Also M is totally geodesic if and only if
 $\frac{1}{2}\lambda v(X) + u((\overline{\nabla}_{\xi}\phi)X) + X\lambda - \frac{1}{2}u(fX) = 0$
(3.25)
for all $X, Y \in TM$.

Proof: As f is parallel then from equation (3.5), we have $2h(X,Y)U = u(X)A_{\overline{N}}Y + u(Y)A_{\overline{N}}X - v(X)fY - v(Y)fX$ Appling u both sides & using (2.12), we have $2(1 - \lambda^2)h(X, Y) = u(X)u(A_{\bar{N}}Y) + u(Y)u(A_{\bar{N}}X) - v(X)u(fY) - v(Y)u(fX)$ (3.26)Replacing Y by U both sides & using (2.12), (2.13) in (3.26), we have $2(1 - \lambda^{2})h(X, U) = u(X)u(A_{\bar{N}}U) + (1 - \lambda^{2})u(A_{\bar{N}}X)$ (3.27) $Ash(X,Y) = g(A_{\overline{N}}X,Y)$ $h(X, U) = g(A_{\overline{N}}X, U) = u(A_{\overline{N}}X)$ So, equations (3.27) reduces as $u(A_{\overline{N}}X) = \frac{\mu}{1-\lambda^2}u(X)$ (3.28)Similarly, we have $u(A_{\overline{N}}Y) = \frac{\mu}{1-\lambda^2}u(Y)$ Where $\mu = h(U, U) = u(A_{\overline{N}}U)$ (3.29)Using (3.28), (3.29) in (3.26), we have $h(X,Y) = \frac{\mu}{(1-\lambda^2)^2} u(X)u(Y) - \frac{1}{2(1-\lambda^2)} (v(X)u(fY) + v(Y)u(fX))$ (3.30)Now putting Y = V and using (2.12), (2.13) in (3.30), we have $h(X,V) = -\frac{1}{2}\lambda v(X) - \frac{1}{2}u(fX)$ Now from (3.30) and (3.31), we have $\frac{1}{2}\lambda v(X) + u((\overline{\nabla}_{\xi}\emptyset)X) + X\lambda - \frac{1}{2}u(fX) = 0.$ (3.31)for all $X, Y \in TM$.

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