# m - projective curvature tensor on a Lorentzian para – Sasakian manifolds

Amit Prakash<sup>1</sup>, Mobin Ahmad<sup>2</sup> and Archana Srivastava<sup>3</sup>

<sup>1</sup>Department of Mathematics, National Institute of Technology, Kurukshetra,

Haryana - 136119, India.

<sup>2</sup>Department of Mathematics, Integral University, Kursi Road Lucknow - 226 026, India, <sup>3</sup>Department of Mathematics, S. R. Institute of Management and Technology, BKT, Lucknow - 227 202, India,

**Abstract:** In this paper we studied m-projectively flat, m-projectively conservative,  $\varphi$ -m-projectively flat LP-Sasakian manifold. It has also been proved that quasi m- projectively flat LP-Sasakian manifold is locally isometric to the unit sphere  $S^n(1)$  if and only if  $M^n$  is m-projectively flat. **Kaywords** – Einstein manifold, m projectively flat, m projectively conservative, quasi m projectively flat

*Keywords* – *Einstein manifold, m-projectively flat, m-projectively conservative, quasi m-projectively flat,*  $\varphi$ -*m-projectively flat.* 

#### I. Introduction

The notion of Lorentzian para contact manifold was introduced by K. Matsumoto. The properties of Lorentzian para contact manifolds and their different classes, viz LP-Sasakian and LSP-Sasakian manifolds have been studied by several authors. In [13], M.Tarafdar and A. Bhattacharya proved that a LP-Sasakian manifold with conformally flat and quasi - conformally flat curvature tensor is locally isometric with a unit sphere  $S^n(1)$ . Further, they obtained that an LP-Sasakian manifold with  $R(X,Y) \cdot \tilde{C} = 0$  is locally isometric with a unit sphere  $S^n(1)$ , where  $\tilde{C}$  is the conformal curvature tensor of type (1, 3) and R(X,Y) denotes the derivation of tensor of tensor algebra at each point of the tangent space. J.P. Singh [10] proved that an m-projectively flat para-Sasakian manifold is an Einstein manifold. He has also shown that if in an Einstein P-Sasakian manifold  $R(\xi, X) \cdot W = 0$  holds, then it is locally isometric with a unit sphere  $H^n(1)$ . Also an n-dimensional  $\eta$ -Einstien P-Sasakian manifold satisfying  $W(\xi, X) \cdot R = 0$  if and only if either manifold is locally isometric to the hyperbolic space  $H^n(-1)$  or the scalar curvature tensor r of the manifold is -n(n-1). S.K. Chaubey [18], studied the properties of m-projective curvature tensor in LP-Sasakian, Einstein LP-Sasakian and  $\eta$ -Einstien LP-Sasakian manifold. LP-Sasakian manifolds have also studied by Matsumoto and Mihai [4], Takahashi [11], De, Matsumoto and Shaikh [2], Prasad & De [9], Venkatesha and Bagewadi[14].

In this paper, we studied the properties of LP-Sasakian manifolds equipped with m-projective curvature tensor. Section 1 is introductory. Section 2 deals with brief account of Lorentzian para-Sasakian manifolds. In section 3, we proved that an m-projectively flat LP-Sasakian manifold is an Einstein manifold and an LP-Sasakian manifold satisfying  $(C_1^1W)(Y,Z) = 0$  is of constant curvature is m-projectively flat. In section 4, we proved that an Einstein LP-Sasakian manifold is m-projectively conservative if and only if the scalar curvature is constant. In section 5, we proved that an n-dimensional  $\varphi$ -m-projectively flat LP-Sasakian manifold is an  $\eta$ -Einstein manifold. In last, we proved that an n-dimensional quasi m - projectively flat LP-Sasakian manifold  $M^n$  is locally isometric to the unit sphere  $S^n(1)$  if and only if  $M^n$  is m-projectively flat.

## II. Preliminaries

An n- dimensional differentiable manifold  $M^n$  is a Lorentzian para-Sasakian (LP-Sasakian) manifold, if it admits a (1, 1) - tensor field  $\phi$ , a vector field  $\xi$ , a 1-form  $\eta$  and a Lorentzian metric g which satisfy

$$\phi^2 X = X + \eta(X)\xi,$$
(2.1)

$$\eta(\xi) = -1, \tag{2.2}$$

$$q(\phi X, \phi Y) = q(X, Y) + n(X)n(Y) \tag{2.3}$$

$$g(\varphi X, \varphi Y) = g(X, Y) + \eta(X)\eta(Y),$$
(2.3)  
$$g(X, \xi) = n(X).$$
(2.4)

$$(D_X\phi)(Y) = g(X,Y)\xi + \eta(Y)X + 2\eta(X)\eta(Y)\xi,$$
(2.5)  
and  $D_Y\xi = \phi X$ 
(2.6)

for arbitrary vector fields X and Y, where D denote the operator of covariant differentiation with respect to Lorentzian metric g, (Matsumoto, (1989) and Matsumoto and Mihai, (1988)). In an LP-Sasakian manifold  $M^n$  with structure( $\phi, \xi, \eta, g$ ), it is easily seen that (a)  $\phi \xi = 0$ (b)  $\eta(\phi X) = 0$  (c) rank  $\phi = (n-1)$ (2.7)Let us put  $F(X, Y) = g(\phi X, Y)$ , (2.8)then the tensor field F is symmetric (0, 2) tensor field F(X,Y) = F(Y,X),(2.9) $F(X,Y) = (D_X\eta)(Y),$ (2.10)and  $(D_X \eta)(Y) - (D_Y \eta)(X) = 0.$ (2.11)An LP- Sasakian manifold  $M^n$  is said to be Einstein manifold if its Ricci tensor S is of the form S(X,Y) = kg(X,Y).(2.12)An LP- Sasakian manifold  $M^n$  is said to be an  $\eta$  -Einstein manifold if its Ricci tensor S is of the form  $S(X,Y) = \alpha g(X,Y) + \beta \eta(X) \eta(Y),$ (2.13)for any vector fields X and Y, where  $\alpha, \beta$  are the functions on  $M^n$ . Let  $M^n$  be an *n*-dimensional LP-Sasakian manifold with structure  $(\varphi, \xi, \eta, g)$ . Then we have (Matsumoto and Mihai, (1998) and Mihai, Shaikh and De,(1999)).  $g(R(X,Y)Z,\xi) = \eta(R(X,Y)Z) = g(Y,Z)\eta(X) - g(X,Z)\eta(Y)$ (2.14)

$$R(\xi, X)Y = g(X, Y)\xi - \eta(Y)X,$$
(2.15)(a)  

$$R(\xi, X)\xi = X + \eta(X)\xi,$$
(2.15)(b)  

$$R(X, Y)\xi = \eta(Y)X - \eta(X)Y,$$
(2.15)(c)  

$$S(X,\xi) = (n-1)\eta(X),$$
(2.16)

 $S(\varphi X, \varphi Y) = S(X, Y) + (n - 1)\eta(X)\eta(Y),$  (2.17) for any vector fields X, Y, Z; where R(X, Y)Z is the Riemannian curvature tensor of type (1, 3). *S* is a Ricci tensor of type (0, 2), *Q* is Ricci tensor of type (1, 1) and *r* is the scalar curvature. g(QX, Y) = S(X, Y) for all *X*, *Y*.

m-projective curvature tensor W on an Riemannian manifold  $(M^n, g)$  (n > 3) of type (1, 3) is defined as follows (G.P.Pokhariyal and R.S. Mishra (1971)).

$$W(X,Y)Z = R(X,Y)Z - \frac{1}{2(n-1)}[S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY],$$
(2.18)

so that  $W(X, Y, Z, U) \stackrel{\text{def}}{=} g(W(X, Y)Z, U) = W(Z, U, X, Y).$ 

On an *n*- dimensional LP-Sasakian manifold, the Concircular curvature tensor *C* is defined as  

$$C(X,Y)Z = R(X,Y)Z - \frac{r}{n(n-1)} [g(Y,Z)X - g(X,Z)Y].$$

Now, in view of  $S(X, Y) = \frac{r}{r}g(X, Y)$ , (2.18) becomes

$$W(X,Y)Z = C(X,Y)Z.$$

Thus, in an Einstein LP-Sasakian manifold, m-projective curvature tensor W and the concircular curvature tensor C concide.

#### III. m-projectively flat LP-Sasakian manifold

In this section we assume that W(X,Y)Z = 0. Then from (2.18), we get

$$R(X,Y)Z = \frac{1}{2(n-1)} [S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY].$$
(3.1)

Contracting (3.1) with respect to *X*, we get

$$S(Y,Z) = \frac{r}{n}g(Y,Z).$$

Hence we can state the following theorem.

**Theorem 3.1:** Let  $M^n$  be an *n*-dimensional m-projectively flat LP-Sasakian manifold, then  $M^n$  be an Einstein manifold.

Contracting (2.18) with respect to X, we get

$$(C_1^1 W)(Y,Z) = S(Y,Z) - \frac{1}{2(n-1)} [nS(Y,Z) - S(Y,Z) + rg(Y,Z) - g(Y,Z)],$$
(3.3)

$$Or, \ (C_1^1 W)(Y,Z) = \frac{n}{2(n-1)} \Big[ S(Y,Z) - \frac{r}{n} g(Y,Z) \Big],$$
(3.4)

where  $(C_1^1 W)(Y, Z)$  is the contraction of W(X, Y)Z with respect to X.

$$= 0$$
, then from (3.4), we get

$$S(Y,Z) = -\frac{1}{n}g(Y,Z).$$
 (3.5)

Using (3.5) in (3.1), we get

If  $(C_1^1 W)(Y, Z)$ 

$$R(X,Y,Z,W) = \frac{r}{n(n-1)} [g(Y,Z)g(X,W) - g(X,Z)g(Y,W)].$$
(3.6)

Hence we can state the following theorem.

**Theorem 3.2.** An m-projectively flat LP-Sasakian manifold satisfying  $(C_1^1 W)(Y, Z) = 0$  is a manifold of constant curvature.

(2.19)

(3.2)

Using (3.5) and (3.6) in (2.18), we get

W(X,Y)Z=0,

i.e. the manifold  $M^n$  is m-projectively flat.

Hence we can state the following theorem.

**Theorem 3.3.** An LP-Sasakian manifold  $(M^n, g)$  (n > 3) satisfying  $(C_1^1 W)(Y, Z) = 0$ , is of constant curvature is m-projectively flat.

## IV. Einstein LP-Sasakian manifold satisfying (div W)(X,Y)Z = 0

**Definition 4.1.** A manifold  $(M^n, g)$  (n > 3) is called m-projectively conservative if (Hicks N.J.(1969)),

$$div(W) = 0, \tag{4.1}$$

where div denotes divergence. Now differentiating (2.18) covariently, we get

$$(D_U W)(X,Y)Z = (D_U R)(X,Y)Z - \frac{1}{2(n-1)} [(D_U S)(Y,Z)X - (D_U S)(X,Z)Y + g(Y,Z)(D_W Q)X - g(X,Z)(D_W Q)Y].$$
(4.2)

Which gives on contraction

 $div(W)(X,Y)Z = div(R)(X,Y)Z - \frac{1}{2(n-1)}[(D_XS)(Y,Z) - (D_YS)(X,Z) + g(Y,Z)div(Q)X - gX,ZdivQY.$ (4.3)

But 
$$div(Q) = \frac{1}{2}dr$$
, using in (4.3), we get

$$div(W)(X,Y)Z = div(R)(X,Y)Z - \frac{1}{2(n-1)} \Big[ (D_X S)(Y,Z) - (D_Y S)(X,Z) + \frac{1}{2} g(Y,Z)dr(X) - 12gX, ZdrY.$$
(4.4)

But from (Eisenhart L.P.(1926)), we have

$$div(R)(X,Y)Z = (D_X S)(Y,Z) - (D_Y S)(X,Z).$$
Using (4.5) in (4.4), we get
(4.5)

$$div(W)(X,Y)Z = \frac{(2n-3)}{2(n-1)} [(D_X S)(Y,Z) - (D_Y S)(X,Z)] - \frac{1}{4(n-1)} [g(Y,Z)dr(X) - g(X,Z)dr(Y)].$$
(4.6)  
If LP Sasakian manifold is an Einstein manifold, then from (1.12) and (4.5), we get

If LP-Sasakian manifold is an Einstein manifold, then from (1.12) and (4.5), we get  

$$div(R)(X,Y)Z = 0.$$
 (4.7)

From (4.6) and (4.7), we get

$$\frac{div(W)(X,Y)Z}{div(W)(X,Y)Z} = -\frac{1}{4(n-1)} [g(Y,Z)dr(X) - g(X,Z)dr(Y)].$$
(4.8)

From (4.1) and (4.8), we get

[g(Y,Z)dr(X) - g(X,Z)dr(Y)] = 0,

which shows that r is constant. Again if r is constant then from (4.8), we get

$$div(W)(X,Y)Z=0.$$

Hence we can state the following theorem.

**Theorem 4.1.** An Einstein LP-Sasakian manifold  $(M^n, g)$  (n > 3) is m-projectively conservative if and only if the scalar curvature is constant.

#### V. $\varphi$ - m-projectively flat LP-Sasakian manifold

 $\begin{aligned} \text{Definition 5.1. A differentiable manifold } & (M^n, g), n > 3, \text{satisfying the condition} \\ & \varphi^2 W(\varphi X, \varphi Y) \varphi Z = 0, \end{aligned} \tag{5.1} \\ \text{is called } \varphi \text{-m - projectively flat LP-Sasakian manifold. (Cabrerizo, Fernandez, Fernandez and Zhen (1999)).} \\ & \text{Suppose that } & (M^n, g), n > 3 \text{ is a } \varphi \text{-m - projectively flat LP-Sasakian manifold. It is easy to see that} \\ & \varphi^2 W(\varphi X, \varphi Y) \varphi Z = 0, \text{ holds if and only if} \\ & g(W(\varphi X, \varphi Y) \varphi Z, \varphi W) = 0, \end{aligned} \\ \text{for any vector fields } & X, Y, Z, W. \\ \text{By the use of } & (2.18), \varphi \text{-m - projectively flat means} \\ & R(\varphi X, \varphi Y, \varphi Z, \varphi W) = \frac{1}{2(n-1)} \begin{bmatrix} S(\varphi Y, \varphi Z) g(\varphi X, \varphi W) - S(\varphi X, \varphi Z) g(\varphi Y, \varphi W) + \\ g(\varphi Y, \varphi Z) S(\varphi X, \varphi W) - g(\varphi X, \varphi Z) S(\varphi Y, \varphi W) \end{bmatrix}, \end{aligned}$ 

where 'R(X, Y, Z, W) = g(R(X, Y)Z, W).

Let  $\{e_1, e_2, \dots, e_{n-1}, \xi\}$  be a local orthonormal basis of vector fields in  $M^n$  by using the fact that  $\{\varphi e_1, \varphi e_2, \dots, \varphi e_{n-1}, \xi\}$  is also a local orthonormal basis, if we put  $X = W = e_i$  in (5.2) and sum up with respect to *i*, then we have

$$\sum_{i=1}^{n-1} {}^{\prime}R(\varphi e_i, \varphi Y, \varphi Z, \varphi e_i) = \frac{1}{2(n-1)} \sum_{i=1}^{n-1} [S(\varphi Y, \varphi Z)g(\varphi e_i, \varphi e_i) - S(\varphi e_i, \varphi Z)g(\varphi Y, \varphi e_i) + g(\varphi Y, \varphi Z)S(\varphi e_i, \varphi e_i) - g(\varphi e_i, \varphi Z)S(\varphi Y, \varphi e_i)].$$
(5.3)

On an LP-Sasakian manifold, we have (*Özgür* (2003))

$$\sum_{\substack{i=1\\n-1}}^{n-1} R(\varphi e_i, \varphi Y, \varphi Z, \varphi e_i) = S(\varphi Y, \varphi Z) + g(\varphi Y, \varphi Z),$$
(5.4)

$$\sum_{i=1}^{n} S(\varphi e_i, \varphi e_i) = r + (n-1),$$
(5.5)

$$\sum_{\substack{i=1\\n-1}}^{n-1} g(\varphi e_i, \varphi Z) S(\varphi Y, \varphi e_i) = S(\varphi Y, \varphi Z),$$
(5.6)

$$\sum_{\substack{i=1\\n-1}} g(\varphi e_i, \varphi e_i) = (n+1),$$
(5.7)

$$\sum_{i=1}^{2} g(\varphi e_i, \varphi Z) g(\varphi Y, \varphi e_i) = g(\varphi Y, \varphi Z),$$
(5.8)

so, by the virtue of (5.4)–(5.8), the equation(5.3) takes the form

$$S(\varphi Y, \varphi Z) = \left[\frac{r}{n-1} - 1\right] g(\varphi Y, \varphi Z).$$
By making the use of (2.3) and (2.17) in (5.9), we get
$$S(Y, Z) = \left[\frac{r}{n-1} - 1\right] g(Y, Z) + \left[\frac{r}{n-1} - n\right] n(Y) n(Z).$$
(5.9)

$$(Y,Z) = \left[\frac{r}{n-1} - 1\right]g(Y,Z) + \left[\frac{r}{n-1} - n\right]\eta(Y)\eta(Z)$$

Hence we can state the following theorem.

**Theorem 5.1.** Let  $M^n$  be an *n*-dimensional n > 3,  $\varphi - m$  - projectively flat LP-Sasakian manifold, then  $M^n$  is an  $\eta$  –Einstein manifold with constants  $\alpha = \left[\frac{r}{n-1} - 1\right]$  and  $\beta = \left[\frac{r}{n-1} - n\right]$ .

#### VI. quasi m-projectively flat LP-Sasakian manifold

**Definition 6.1.** An LP-Sasakian manifold  $M^n$  is said to be quasi m-projectively flat, if  $g(W(X,Y)Z,\varphi U)=0,$ (6.1)for any vector fields X, Y, Z, U.

From (2.18), we get

$$g(W(X,Y)Z,\varphi U) = g(R(X,Y)Z,\varphi U) - \frac{1}{2(n-1)} [S(Y,Z)g(X,\varphi U) - S(X,Z)g(Y,\varphi U) + g(Y,Z)S(X,\varphi U) - g(X,Z)S(Y,\varphi U)].$$
(6.2)

Let  $\{e_1, e_2, \dots, e_{n-1}, \xi\}$  be a local orthonormal basis of vector fields in  $M^n$  by using the fact that  $\{\varphi e_1, \varphi e_2, \dots, \varphi e_{n-1}, \xi\}$  is also a local orthonormal basis, if we put  $X = \varphi e_i$ ,  $U = e_i$  in (5.2) and sum up with respect to *i*, then we have

$$\sum_{i=1}^{n-1} g(W(\varphi e_i, Y)Z, \varphi e_i) = \sum_{i=1}^{n-1} g(R(\varphi e_i, Y)Z, \varphi e_i) - \frac{1}{2(n-1)} \sum_{i=1}^{n-1} [S(Y, Z)g(\varphi e_i, \varphi e_i) - S(\varphi e_i, Z)g(Y, \varphi e_i) + g(Y, Z)S(\varphi e_i, \varphi e_i) - g(\varphi e_i, Z)S(Y, \varphi e_i)].$$
(6.3)

On an LP-Sasakian manifold by straight forward calculation, we get 
$$n-1$$

$$\sum_{\substack{i=1\\n-1}}^{n-1} {}^{\prime}R(e_i, Y, Z, e_i) = \sum_{i=1}^{n-1} {}^{\prime}R(\varphi e_i, Y, Z, \varphi e_i) = S(Y, Z) + g(\varphi Y, \varphi Z),$$
(6.4)

$$\sum_{i=1}^{N} S(\varphi e_i, Z)g(Y, \varphi e_i) = S(Y, Z) - (n-1)\eta(Y)\eta(Z).$$
(6.5)

Using (5.4), (5.7), (6.4), (6.5) in (6.3), we get  

$$\sum_{i=1}^{n-1} g(W(\varphi e_i, Y)Z, \varphi e_i) = S(Y, Z) + g(\varphi Y, \varphi Z)$$

m-projective curvature tensor on a Lorentzian para – Sasakian manifolds

$$-\frac{1}{2(n-1)}[(n-1)S(Y,Z) + (r+n-1)g(Y,Z) + 2(n-1)\eta(Y)\eta(Z)].$$
(6.6)

Using (2.3) in (6.6), we get

$$\sum_{i=1}^{n-1} g(W(\varphi e_i, Y)Z, \varphi e_i) = \frac{1}{2} \Big[ S(Y, Z) - \left(\frac{r}{n} - 1\right) g(Y, Z) \Big].$$
(6.7)

If  $M^n$  is quasi m-projectively flat, then (6.7) reduces to

$$S(Y,Z) = \left(\frac{r}{n} - 1\right)g(Y,Z). \tag{6.8}$$

Putting  $Z = \xi$  in (6.8) and then using (2.6) and (2.16), we get r = n(n-1). (6.9)

Using (6.9) in (6.8), we get

$$S(Y,Z) = (n-1)g(Y,Z).$$
 (6.10)

i.e.  $M^n$  is an Einstein manifold.

Now using (6.10) in (2.18), we get W(V,V) = P(V,V) = [P(V,Z)V]

$$W(X,Y)Z = R(X,Y)Z - [g(Y,Z)X - g(X,Z)Y].$$
(6.11)  
If LP-Sasakian manifold is m-projectively flat, then from (6.11), we get

$$R(X,Y)Z = [g(Y,Z)X - g(X,Z)Y].$$
(6.12)

Hence we can state the following theorem.

**Theorem 6.2.** A quasi m-projectively flat LP-Sasakian manifold  $M^n$  is locally isomeric to the unit sphere  $S^n(1)$  if and only if  $M^n$  is m-projectively flat.

#### References

- [1] D. E. Blair, Contact manifolds on Riemannian geometry, Lecture Notes in Mathematics, Vol.509, Spinger-Verlag, Berlin, 1976.
- [2] U. C. De, K. Matsumoto and A. A. Shaikh, On Lorentzian para-Sasakian manifolds, Rendicontidel Seminario Mathematico di Messina, Series II, Supplemento al 3 (1999), 149-158.
- [3] K. Matsumoto, On Lorentzian para-contact manifolds, Bull. Of Yamagata Univ. Nat. Sci., 12 (1989), 151-156.
- [4] K. Matsumoto, I. Mihai, On certain transformation in a Lorentzian para-Sasakian manifold, Tensor N.S., 47 (1988), 189-197.
- [5] R. H. Ojha, A notes on the m-projective curvature tensor, Indian J. Pure Applied Math., 8 (1975), No. 12, 1531-1534.
- [6] R. H. Ojha, On Sasakian manifold, Kyungpook Math. J., 13 (1973), 211-215.
- [7] G. P. Pokhariyal and R. S. Mishra, Curvature tensor and their relativistic significance II, Yokohama Mathematical Journal, 19 (1971), 97-103.
- [8] S. Prasad and R. H. Ojha, Lorentzian para contact submanifolds, Publ. Math. Debrecen, 44/3-4 (1994), 215-223.
- [9] A. A. Shaikh and U. C. De, On 3-dimensional LP-Sasakian manifolds, Soochow J. of Math., 26 (4) (2000), 359-368.
- [10] J. P. Singh, On an Einstein m-projective P-Sasakian manifolds, (2008) (to appear in Bull. Cal. Math. Soc.).
- [11] T. Takahashi, Sasakian  $\phi$  –symmetric spaces, Tohoku Math. J., 29 (1977), 93-113.
- [12] S. Tanno, Curvature tensors and non-existance of killing vectors, Tensor N. S., 2(1971), 387-394.
- [13] M. Tarafdar and A. Bhattacharya, On Lorentzian para-Sasakian manifolds, Steps in Differential Geometry, Proceeding of the Colloquium of Differential Geometry, 25-30 july 2000, Debrecen, Hungry, 343-348.
- [14] Venkatesha and C. S. Begewadi, On concircular  $\phi$ -recurrent LP-Sasakian Manifolds, Differential Geometry-Dynamical Systems, 10 (2008), 312-319.
- [15] K. Tano, and M. Kon, Structures on manifolds, Series in Pure Mathematics, Vol. 3, World Scientific, Singapore, 1984.
- [16] A. Taleshian and N. Asghari, On LP-Sasakian manifolds satisfying certain conditions on the concircular curvature tensor, Differential Geometry-Dynamical Systems, 12,(2010), 228-232.
- [17] S. K. Chaubey and R. H. Ojha, On the m-projective curvature tensor of a Kenmotsu manifold, Differential Geometry-Dynamical Systems, 12,(2010), 1-9.
- [18] S. K. Chaubey, Some properties of LP-Sasakian manifolds equipped with m-projective curvature tensor, Bulletin of Mathematical Analysis and applications, 3 (4), (2011), 50-58.

(- 1 1)