On Ø- Concircurlarly Symmetric Para Sasakian Manifold

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Abstract : The present paper deals with the study of \emptyset - concircurlarly symmetric Para Sasakian manifold and have study locally and globally \emptyset - concircurlarly symmetric Para Sasakian manifold.further we have shown that globally symmetry and globally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly of \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - concircurlarly symmetric are equivalent.Next we study 3 – dimensional locally \emptyset - dimensi

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Introduction:

A transformation of an n-dimensional Riemannian manifold M, which transform every geodesic circle of M in to a geodesic circle, is called a concircular transformation. A concircular transformation is always a conformal transformation. Here geodesic circle means a curve in M whose first curvature is constant and second curvature is identically zero. Thus the geometry of concircular transformations, that is, the concircular geometry, is a generalization of inversive geometry in the sence that the change of metric is more general than that induced by a circle preserving diffeomorphism. An interesting invariant of a concircular transformation . an interesting invariant of a concircular transformation is the concircular curvature tensor. A (1,3) type of tensor C(X, Y)Z which remains invariant under concircular transformation for n dimensional Riemanniam manifold is given by [4]

(1.1)
$$C(X,Y)Z = R(X,Y)Z - \frac{r}{r(r-1)}[g(Y,Z)X - g(X,Z)Y]$$

Where R is the Riemannian curvature tensor, r is the scalar curvature tensor. from (1.1) we obtain

(1.2)
$$(D_W C)(X, Y)Z = (D_W R)(X, Y)Z - \frac{dr(w)}{n(n-1)} [g(Y, Z)X - g(X, Z)Y]$$

I.

In this paper we study of ϕ - concircurlarly symmetric Para Sasakian manifold we have also study locally and globally ϕ - concircurlarly symmetric Para Sasakian manifold and shown that globally symmetry and globally ϕ - concircurlarly symmetric are equivalent. Next we have study 3 – dimensional locally ϕ - concircurlarly symmetric Para Sasakian manifold and shown some interesting result.

A contact manifold is said locally \emptyset - concircularly symmetric if the concircular curvature tensor C satisfies (1.3) $\emptyset^2((D_x C)(Y, Z, W)) = 0$

For horizontal vector fields $X, Y, Z \in X_n M$ holds on M. If X, Y, Z and W are arbitrary vector fields the manifold is called Globally \emptyset - concircurlarly symmetric.

II. Preliminaries:

Let $M^n(\emptyset, \xi, \eta, g)$ be an almost contact Riemannian manifold ,where \emptyset is a tensor field of type (1,1), ξ is the structure vector field , η is a 1-form and g is the Riemannian metric which satisfy

- (2.1) $\emptyset^2 X = X \eta(X)\xi$
- (2.2) (a) $\eta(\xi) = 1$ (b) $g(X,\xi) = \eta(X)$ (c) $\eta(\emptyset X) = 0$ (d) $\emptyset \xi = 0$
- (2.3) $g(\emptyset X, \emptyset Y) = -g(X, Y) \eta(X)\eta(Y)$
- (2.4) $(D_X \phi)(Y) = -G(X, Y) \eta(Y)X + 2\eta(X)\eta(Y)\xi$
- (2.5) (a) $D_X \xi = \emptyset X$, (b) $(D_X \eta)(Y) = g(\emptyset X, Y)$, (c) $d\eta = 0$

For all vector field X,Y,Z where D denotes the operator of covariant differentiation with respect to g, the manifold $M^n(\phi, \xi, \eta, g)$ is called a Para –Sasakian manifold or briefly a P – Sasakian manifold. [2-8]. In a Para Sasakian manifold, the following relation holds [1,2,6]

(2.6) $\eta(R(X,Y)Z) = g(X,Z)\eta(Y) - g(Y,Z)\eta(X)$

- (2.7) $R(X,Y)\xi = \eta(X)Y \eta(Y)X$
- (2.8) $S(\phi X, \phi Y) = S(X, Y) + (n-1)\eta(X)\eta(Y)$
- (2.9) $S(X,\xi) = -(n-1)\eta(X)$

For all vector fields X, Y, Z, where S is the Ricci Tensor of type (0,2) and R is the Riemannian curvature tensor of the manifold.

For a 3 – dimensional Para Sasakian manifold, we have [4]

(2.10)
$$R(X,Y)Z = \left(\frac{r+4}{2}\right) [g(Y,Z)X - g(X,Z)Y] - \left(\frac{r+6}{2}\right) [g(Y,Z)\eta(X)\xi - g(X,Z)\eta(Y)\xi + \eta Y \eta Z X - \eta X \eta Z Y]$$

(2.11) $S(X,Y) = \frac{1}{2} [(r+2)g(X,Y) - (r+6)\eta(X)\eta(Y)]$

For all vector fields X, Y, Z, where S is the Ricci Tensor of type (0,2) and R is the curvature tensor of the type (1,3) and r is scalar curvature of the manifolds.

If the Ricci tensor S of the manifold is of the form $S(X, Y) = \lambda g(X, Y)$, where λ is a constant and $X, Y \in X_n M$, then the manifold is Einstein manifold.

III. Globally Ø- concircularly symmetric para sasakian manifold:

Definition (3.1): A Para Saskian manifold M is said to be Globally Ø- concircularly symmetric if the concircular curvature tensor C satisfies

$$(3.1) \qquad \qquad \emptyset^2\bigl((D_X C)(Y,Z,W)\bigr) = 0$$

For all vector fields $X, Y, Z \in X_n M$.

Let us suppose that M is globally \emptyset - concircularly symmetric Para Sasakian manifold then by the def (3.1), we have

$$\phi^2\big((D_W C)(X,Y,Z)\big)=0$$

Using (2.1), we have

 $(D_W C)(X, Y)Z - \eta(((D_W C)(X, Y)Z)\xi = 0$ From it follows that

 $g((D_W C)(X, Y)Z, U) - \eta(((D_W C)(X, Y)Z)\eta(U) = 0$

Using (1.4) in above we get

$$(3.2) \quad g((D_W R)(X,Y)Z,U) - \frac{dr(w)}{n(n-1)} [g(Y,Z)g(X,U) - g(X,Z)g(Y,U)] - \eta(((D_W R)(X,Y)Z)\eta(U) + \frac{dr(W)}{n(n-1)} [g(Y,Z)\eta(X) - g(X,Z)\eta(Y)]\eta(U) = 0$$

Let $(e_i), i = 1,2,3...,n$ be orthnormal basis of the tangent space at any point of the manifold the putting $X = U = e_i$ in (3.2) and taking summation over i, we get (3.3)

$$0 = (D_w S)(Y,Z) - \frac{dr(W)}{n} g(Y,Z) - \eta(((D_w R)(e_i,Y)Z)\eta(e_i) + \frac{dr(W)}{n(n-1)}[g(Y,Z) - \eta(Y)\eta(Z)]$$

Putting $z = \xi$ in (3.3) and using , we get

(3.4) $(D_w S)(Y,\xi) - \frac{dr(W)}{n} \eta(Y) - \eta(((D_W R)(e_i, Y)\xi)\eta(e_i) = 0$ After simplification , we get $\eta(((D_W R)(e_i, Y)\xi)\eta(e_i) = 0$

After simplification , we get $\eta(((D_W R)(e_i, Y)\xi)\eta(e_i))$ Then from (3.4), we have

(3.5)
$$(D_w S)(Y,\xi) = \frac{1}{n} dr(W) \eta(Y)$$

Putting $Y = \xi$, we get dr(w) = 0 and this implies r is constant. So from (3.5) we have $(D_w S)(Y, \xi) = 0$ and this implies that

S(Y,W) = -(n-1)g(Y,W), Hence we state the following

Theorem (3.1): If a Para Saskian manifold is globally \emptyset – concircularly symmetric, then manifold is Einstein manifold.

Further it is also well known that if the Ricci tensor S of the manifold is of the form $S(X,Y) = \lambda g(X,Y)$, where λ is constant and $X,Y \in X_n M$, then the manifold is Einstein manifold.

Now let us suppose that $S(X,Y) = \lambda g(X,Y)$, that is manifold is Einstein manifold then from (1.3), we have $(D_W C)(X,Y)Z = (D_W R)(X,Y)Z$

Apply \emptyset^2 both side , we get

 $\phi^2(D_W C)(X,Y)Z = \phi^2(D_W R)(X,Y)Z$, Hence we state following

Theorem (3.2): A globally \emptyset – concircularly symmetric para Saskian manifold is globally \emptyset – symmetric. Since a globally \emptyset – symmetric para Saskian manifold is always globally \emptyset – concircularly symmetric manifold then by theorem (3.2) we have

Theorem (3,3): On a para Saskian manifold globally \emptyset – symmetric and globally \emptyset – concircularly symmetric are equivalent.

3- dimensional Locally \emptyset –concircularly symmetric para Sasakian manifold: IV. In a 3 dimensional para Sasakian manifold concircular curvature tensor is given by (4.1) $C(X,Y)Z = {\binom{r+4}{2}} [g(Y,Z)X - g(X,Z)Y] - {\binom{r+6}{2}} [g(Y,Z)\eta(X)\xi - g(X,Z)\eta(Y)\xi + \eta(Y)\eta(Z)X - \etaX\eta ZY - r6gY,ZX - gX,ZY]$

Taking covariant differentiation of (4.1), we get $(D_{W}C)(X V)$

$$= \frac{dr(w)}{2} [g(Y,Z)X - g(X,Z)Y] - \frac{dr(w)}{2} [g(Y,Z)\eta(X)\xi - g(X,Z)\eta(Y)\xi + \eta(Y)\eta(Z)X - \eta(X)\eta(Z)Y] - (\frac{r+6}{2}) [g(Y,Z)(D_W\eta)(X)\xi + g(Y,Z)\eta(X)(D_W\xi) - g(X,Z)(D_W\eta)(Y)\xi - g(X,Z)\eta(Y)(D_W\xi) + (D_W\eta)(Y)\eta(Z)X + (D_W\eta)(Z)\eta(Y)X - (D_W\eta)(X)\eta(Z)X - (D_W\eta)(Z)\eta(X)Y] - \frac{dr(w)}{6} [[g(Y,Z)X - g(X,Z)Y]]$$

Taking X, Y, Z horizontal vector field and using (2.5) and (2.6), we get

(4.3)
$$(D_W C)(X,Y)Z = \frac{dr(w)}{3} [g(Y,Z)X - g(X,Z)Y] \\ - \left(\frac{r+6}{2}\right) [g(Y,Z)g(X,W) - g(X,Z)g(Y,W)]\xi$$

From (4.3), it follows that

(4.2)

Theorem (4.1): A 3-dimensional Para Sasakian manifold is locally ϕ – concircularly symmetric if and only if scalar curvature r is constant.

In 1977[4] has proved that

Corollarly (4.2): A 3-dimensional Para sasakian manifold is locally \emptyset – symmetric if and only if scalr curvature r is constant.

Using corollary (4.2) we state the following

Theorem (4.3): A 3-dimensional Para Sasakian manifold is locally ϕ – concircularly symmetric if and only if it is locally ϕ – symmetric.

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